

A characterization of ruled hypersurfaces and homogeneous real hypersurfaces of type (A_0) , (A_1) , and (B) in non-flat complex space forms

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Dedicated to Professor U-Hang Ki and Professor Masafumi Okumura on the occasion of their 80th birthdays

Abstract. The purpose of this paper is to give a characterization of ruled hypersurfaces and homogeneous real hypersurfaces of type (A_0) , (A_1) , and (B) in non-flat complex space forms by using the second covariant derivatives of the shape operators.

1. Introduction

Let $\overline{M}_n(c)$ be an n -dimensional complex space form with constant holomorphic sectional curvature $c \neq 0$, and let J and g be its complex structure and Kähler metric, respectively. Complete and simply connected complex space forms are isometric to either a complex projective space $\mathbb{C}P_n(c)$ or a complex hyperbolic space $\mathbb{C}H_n(c)$ decided from $c > 0$ or $c < 0$, respectively.

Let M be a connected submanifold of $\overline{M}_n(c)$ with real codimension 1. We refer to this simply as a real hypersurface below. The induced metric of M is denoted by g . For a local unit normal vector field ν of M , we define the structure vector ξ of M by $\xi = -J\nu$. Further, the structure tensor field ϕ is defined by $JX = \phi X + g(X, \xi)\nu$. The structure vector ξ is said to be

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principal if $A\xi = \alpha\xi$ is satisfied for some function α , where A is the shape operator of M .

A real hypersurface M is said to be a Hopf hypersurface if the structure vector ξ of M is principal. In a complex projective space $\mathbb{C}P_n(c)$, Hopf hypersurfaces with constant principal curvatures are simply the homogeneous real hypersurfaces (for details, see §2 Theorem K). They were classified by R. Takagi [14] (for details, see §2 Theorem T), and their principal curvatures were also calculated by R. Takagi [15] (for details, see §2). In a complex hyperbolic space $\mathbb{C}H_n(c)$, Hopf hypersurfaces with constant principal curvatures were classified by J. Berndt [2] (for details, see §2 Theorem B).

On the other hand, there are important examples of non-Hopf hypersurfaces in $\overline{M}_n(c)$, such as ruled hypersurfaces (for definition, see §2), with a totally geodesic ruling along a curve in $\overline{M}_n(c)$.

For a real hypersurface M in $\overline{M}_n(c)$, let T_0 be a distribution defined by $T_0 = \{X \in TM \mid g(X, \xi) = 0\}$, where TM denotes the tangent bundle of M . The distribution T_0 is called a holomorphic distribution (see [9]). T_0 is not integrable on any Hopf homogeneous real hypersurface of $\overline{M}_n(c)$ but is integrable on any ruled hypersurface of $\overline{M}_n(c)$. M. Kimura [5] obtained some properties of a ruled hypersurface of $\mathbb{C}P_n(c)$ and gave an example of minimal ruled hypersurface of $\mathbb{C}P_n(c)$. There are many characterization theorems of ruled hypersurfaces in $\overline{M}_n(c)$ (e.g., [1], [4], [6], [7], [9]). We also know many characterization theorems of homogeneous real hypersurfaces by using some formulas of the first covariant derivatives of the shape operators (e.g., [3], [7], [8], [9]).

In [12], we characterized homogeneous real hypersurfaces of type (A₀) and (B) simultaneously by using the second covariant derivatives of the shape operators under the conditions that the structure vector fields ξ are principal as follows:

Theorem N.[12][Theorem 4.1.] *Let M be a connected real hypersurface in a complex space form $\overline{M}_n(c)$ ($n \geq 2$, $c \neq 0$) on which the structure vector ξ is principal with principal curvature $\alpha \neq 0$. Then the shape operator A*

satisfies

$$g((\nabla_{X,Y}^2 A)Z, W) = \frac{\alpha}{4} \left\{ g(\phi AX, Y)g((4\phi A + \frac{2c}{\alpha}\phi)Z, W) \right. \\ \left. + g(\phi AX, Z)g((4\phi A + \frac{c}{\alpha}\phi)Y, W) \right. \\ \left. + g(\phi AX, W)g((4\phi A + \frac{c}{\alpha}\phi)Y, Z) \right\},$$

$$X, Y, Z, W \in T_0,$$

if and only if M is locally congruent to a homogeneous real hypersurface of type (A_0) or (B) .

The purpose of this paper is to generalize the above result. To that end, we prove the following theorem:

Theorem 4.1. *Let M be a connected real hypersurface in a complex space form $\overline{M}_n(c)$ ($n \geq 3$, $c \neq 0$). Then the shape operator A satisfies the following equation for some nonzero constant a :*

$$g((\nabla_{X,Y}^2 A)Z, W) = \frac{c}{4a} \left\{ 2g(\phi AX, Y)g((2\phi A + a\phi)Z, W) \right. \\ \left. + g(\phi AX, Z)g((4\phi A + a\phi)Y, W) \right. \\ \left. + g(\phi AX, W)g((4\phi A + a\phi)Y, Z) \right\}, \tag{4.1}$$

$$X, Y, Z, W \in T_0,$$

if and only if M is locally congruent to one of the following:

- (A_0) a horosphere in $\mathbb{C}H_n(c)$;
- (A_1) a geodesic hypersphere in $\overline{M}_n(c)$ or a tube over a complex hyperbolic hyperplane $\mathbb{C}H_{n-1}(c)$ in $\mathbb{C}H_n(c)$;
- (B) a tube over a totally geodesic and totally real space form of real dimension n in $\overline{M}_n(c)$;
- (R) a ruled hypersurface in $\overline{M}_n(c)$.

In the following all manifolds are assumed to be C^∞ and connected.

2. Preliminaries

In this section, we present some preliminary results of real hypersurfaces in a complex space form.

Let $\overline{M}_n(c)$ ($c \neq 0$) be an n -dimensional complex space form with constant holomorphic sectional curvature c and let J and g be its complex structure and Kähler metric, respectively.

M is a real hypersurface of $\overline{M}_n(c)$. Further, we denote by g the induced Riemannian metric on M and by ν a local unit normal vector field along M in $\overline{M}_n(c)$.

The Gauss and Weingarten formulas are:

$$\overline{\nabla}_X Y = \nabla_X Y + g(AX, Y)\nu, \quad (2.1)$$

$$\overline{\nabla}_X \nu = -AX, \quad (2.2)$$

where $\overline{\nabla}$ and ∇ respectively denote the Levi-Civita connection on $\overline{M}_n(c)$ and M , and A is the shape operator of M in $\overline{M}_n(c)$.

We define an almost contact metric structure (ϕ, ξ, η, g) on M as in the usual way:

$$\xi = -J\nu, \quad \eta(X) = g(X, \xi), \quad \phi X = (JX)^T, \quad X \in TM, \quad (2.3)$$

where $()^T$ denotes the tangential component of a vector. These structure tensors satisfy the following equations:

$$\phi^2 = -I + \eta \otimes \xi, \quad \phi\xi = 0, \quad \eta \circ \phi = 0, \quad \eta(\xi) = 1, \quad (2.4)$$

where I denotes the identity mapping of TM .

From (2.1) and (2.3), we easily have

$$(\nabla_X \phi)Y = \eta(Y)AX - g(AX, Y)\xi, \quad (2.5)$$

$$\nabla_X \xi = \phi AX, \quad (2.6)$$

for tangent vectors $X, Y \in TM$.

In our case the Gauss and Codazzi equations of M become

$$\begin{aligned} R(X, Y)Z = & \frac{c}{4} \{g(Y, Z)X - g(X, Z)Y + g(\phi Y, Z)\phi X \\ & - g(\phi X, Z)\phi Y - 2g(\phi X, Y)\phi Z\} \\ & + g(AY, Z)AX - g(AX, Z)AY, \end{aligned} \quad (2.7)$$

$$(\nabla_X A)Y - (\nabla_Y A)X = \frac{c}{4} \{ \eta(X)\phi Y - \eta(Y)\phi X - 2g(\phi X, Y)\xi \}. \quad (2.8)$$

The Ricci formula of the tensor field T on M is:

$$\nabla_{X,Y}^2 T - \nabla_{Y,X}^2 T = R(X, Y) \cdot T, \quad X, Y \in TM, \quad (2.9)$$

where the second covariant derivative $\nabla_{X,Y}^2 T$ of T is defined by

$$\nabla_{X,Y}^2 T = \nabla_X(\nabla_Y T) - \nabla_{\nabla_X Y} T$$

and $R(X, Y)$ acts on T as a derivation.

A real hypersurface M of $\mathbb{C}P_n(c)$ is said to be a homogeneous real hypersurface if it is an orbit of an analytic subgroup of the isometry group of $\mathbb{C}P_n(c)$. We know the complete classification of homogeneous real hypersurfaces of $\mathbb{C}P_n(c)$.

Theorem T ([14]). *Let M be a homogeneous real hypersurface of $\mathbb{C}P_n(c)$. Then M is locally congruent to one of the following spaces:*

- (A₁) *a geodesic hypersphere;*
- (A₂) *a tube of radius r ($0 < r < \frac{\pi}{\sqrt{c}}$) over a totally geodesic $\mathbb{C}P_k(c)$ ($1 \leq k \leq n - 2$);*
- (B) *a tube of radius r ($0 < r < \frac{\pi}{2\sqrt{c}}$) over a complex quadric Q_{n-1} ;*
- (C) *a tube of radius r ($0 < r < \frac{\pi}{2\sqrt{c}}$) over $\mathbb{C}P_1 \times \mathbb{C}P_{\frac{n-1}{2}}$ where n (≥ 5) is odd;*
- (D) *a tube of radius r ($0 < r < \frac{\pi}{2\sqrt{c}}$) over a complex Grassmann $G_{2,5}$ and $n = 9$;*
- (E) *a tube of radius r ($0 < r < \frac{\pi}{2\sqrt{c}}$) over a Hermitian symmetric space $SO(10)/U(5)$ and $n = 15$.*

For homogeneity of a real hypersurface in $\mathbb{C}P_n(c)$, there is a criterion obtained by M. Kimura [5]. His theorem is

Theorem K ([5]). *Let M be a connected real hypersurface in $\mathbb{C}P_n(c)$. Then M has constant principal curvatures and the structure vector ξ is*

principal if and only if M is congruent to an open subset of a homogeneous real hypersurface.

In $\mathbb{C}H_n(c)$ J. Berndt [2] obtained the complete classification of Hopf hypersurfaces with constant principal curvatures. His theorem is the following:

Theorem B ([2]). *Let M be a connected real hypersurface of $\mathbb{C}H_n(c)$ ($n \geq 2$) with constant principal curvatures. Further, assume that the structure vector ξ is principal. Then M is orientable and holomorphic congruent to an open part of one of the following hypersurfaces:*

(A₀) *a horosphere in $\mathbb{C}H_n(c)$;*

(A₁) *a geodesic hypersphere or a tube over a complex hyperbolic hyperplane $\mathbb{C}H_{n-1}(c)$ in $\mathbb{C}H_n(c)$;*

(A₂) *a tube of radius $r \in \mathbb{R}_+$ over a totally geodesic $\mathbb{C}H_k(c)$ ($1 \leq k \leq n-2$);*

(B) *a tube of radius $r \in \mathbb{R}_+$ over a totally geodesic totally real submanifold $\mathbb{R}H_n$.*

Concerning the principal curvatures α , λ_1 , λ_2 , λ_3 , λ_4 and their multiplicities m_α , m_{λ_1} , m_{λ_2} , m_{λ_3} , m_{λ_4} of homogeneous real hypersurfaces in $\mathbb{C}P_n(c)$, we have the following Table 1 (see [15]): Here, α is the principal curvature corresponding to the principal direction ξ .

Concerning the principal curvatures α , λ_1 , λ_2 and their multiplicities m_α , m_{λ_1} , m_{λ_2} of Hopf homogeneous real hypersurfaces in $\mathbb{C}H_n(c)$, we have the following Table 2 (see [10]): Here, α is the principal curvature corresponding to the principal direction ξ .

Next, we explain some fundamental facts of ruled hypersurfaces in complex space forms (for details, see [1], [4], [5], [6]). Let $\gamma : I \rightarrow \overline{M}_n(c)$ be an arbitrary (regular) curve in $\overline{M}_n(c)$. Then for every $t \in I$ there exists a totally geodesic hyperplane $\overline{M}_{n-1}^{(t)}(c)$ (in $\overline{M}_n(c)$) through the point $\gamma(t)$ which is orthogonal to the holomorphic plane spanned by $\gamma'(t)$ and $J\gamma'(t)$. Let $M = \bigcup_{t \in I} \overline{M}_{n-1}^{(t)}(c)$. Then M obtains a real hypersurface of $\overline{M}_n(c)$, which is called a ruled hypersurface.

Type	Principal curvatures	Multiplicities
(A ₁)	$\alpha = \sqrt{c} \cot \sqrt{cr}$ $\lambda_1 = \frac{\sqrt{c}}{2} \cot \frac{\sqrt{c}}{2} r$	$m_\alpha = 1$ $m_{\lambda_1} = 2(n-1)$
(A ₂)	$\alpha = \sqrt{c} \cot \sqrt{cr}$ $\lambda_1 = \frac{\sqrt{c}}{2} \cot \frac{\sqrt{c}}{2} r$ $\lambda_2 = -\frac{\sqrt{c}}{2} \tan \frac{\sqrt{c}}{2} r$	$m_\alpha = 1$ $m_{\lambda_1} = 2(n-k-1)$ $m_{\lambda_2} = 2k$
(B)	$\alpha = \sqrt{c} \cot \sqrt{cr}$ $\lambda_1 = \frac{\sqrt{c}}{2} \cot \frac{\sqrt{c}}{2} (r - \frac{\pi}{2\sqrt{c}})$ $\lambda_2 = -\frac{\sqrt{c}}{2} \tan \frac{\sqrt{c}}{2} (r - \frac{\pi}{2\sqrt{c}})$	$m_\alpha = 1$ $m_{\lambda_1} = n-2$ $m_{\lambda_2} = n-2$
(C)	$\alpha = \sqrt{c} \cot \sqrt{cr}$ $\lambda_i = \frac{\sqrt{c}}{2} \cot \frac{\sqrt{c}}{2} (r - \frac{\pi i}{2\sqrt{c}})$ ($i = 1, 2, 3, 4$)	$m_\alpha = 1$ $m_{\lambda_i} = n-3$ ($i = 2, 4$) $m_{\lambda_i} = 2$ ($i = 1, 3$)
(D)	$\alpha = \sqrt{c} \cot \sqrt{cr}$ $\lambda_i = \frac{\sqrt{c}}{2} \cot \frac{\sqrt{c}}{2} (r - \frac{\pi i}{2\sqrt{c}})$ ($i = 1, 2, 3, 4$)	$m_\alpha = 1$ $m_{\lambda_i} = 4$ ($i = 1, 2, 3, 4$)
(E)	$\alpha = \sqrt{c} \cot \sqrt{cr}$ $\lambda_i = \frac{\sqrt{c}}{2} \cot \frac{\sqrt{c}}{2} (r - \frac{\pi i}{2\sqrt{c}})$ ($i = 1, 2, 3, 4$)	$m_\alpha = 1$ $m_{\lambda_i} = 8$ ($i = 2, 4$) $m_{\lambda_i} = 6$ ($i = 1, 3$)

Table 1: Principal curvatures in $\mathbb{C}P_n(c)$

Type	Principal curvatures	Multiplicities
(A ₀)	$\alpha = \sqrt{-c}$ $\lambda_1 = \frac{\sqrt{-c}}{2}$	1 $2n-2$
(A)	$\alpha = \sqrt{-c} \coth \sqrt{-cr}$ $\lambda_1 = \frac{\sqrt{-c}}{2} \coth \frac{\sqrt{-c}}{2} r$ $\lambda_2 = \frac{\sqrt{-c}}{2} \tanh \frac{\sqrt{-c}}{2} r$	1 $2(n-k-1)$ $2k$
(B)	$\alpha = \sqrt{-c} \tanh \sqrt{-cr}$ $\lambda_1 = \frac{\sqrt{-c}}{2} \coth \frac{\sqrt{-c}}{2} r$ $\lambda_2 = \frac{\sqrt{-c}}{2} \tanh \frac{\sqrt{-c}}{2} r$	1 $n-1$ $n-1$

Table 2: Principal curvatures in $\mathbb{C}H_n(c)$

Let $T_0 = \{X \in TM \mid X \perp \xi\}$ be the holomorphic distribution of M . Then the distribution T_0 is integrable on a ruled hypersurface M . Fur-

thermore, the shape operator A of M satisfies the following:

$$\begin{aligned} A\xi &= \alpha\xi + U \quad (U \neq 0), \\ AU &= g(U, U)\xi, \\ AX &= 0, \quad X \perp \xi, \quad U, \end{aligned} \tag{2.10}$$

where U is the T_0 -component of $A\xi$ (for details, see [6]).

Now, we define the concept of η -parallel second fundamental form as follows.

Definition 2.1. *The shape operator A of a real hypersurface M is said to be η -parallel if A satisfies the following:*

$$g((\nabla_X A)Y, Z) = 0, \quad X, Y, Z \in T_0. \tag{2.11}$$

There are many characterization theorems for ruled hypersurfaces in a complex space form (see, for example, [1], [4], [5], [6], [7]). The following proposition can be easily deduced:

Proposition 2.2. *Let M be a real hypersurface of a complex space form $\overline{M}_n(c)$. If the shape operator A of M satisfies*

$$g(AX, Y) = 0, \quad X, Y \in T_0, \tag{2.12}$$

then M is locally congruent to a ruled hypersurface of $\overline{M}_n(c)$.

Proof Let X and Y be vector fields of M whose values belong to T_0 . Then, according to (2.6) and (2.12), we have

$$g(\nabla_X Y, \xi) = -g(Y, \phi AX) = g(AX, \phi Y) = 0.$$

This means that

$$\nabla_X Y \in T_0, \quad X, Y \in T_0. \tag{2.13}$$

Furthermore, for vector fields X and Y whose values belong to T_0 , we have

$$\overline{\nabla}_X Y = \nabla_X Y + g(AX, Y)\nu = \nabla_X Y. \tag{2.14}$$

From (2.13) and (2.14), we conclude that the leaves of the distribution T_0 are totally geodesic in M and in $\overline{M}_n(c)$. Because T_0 is J -invariant, all the leaves of the distribution T_0 are totally geodesic complex hyperplanes $\overline{M}_{n-1}(c)$ of $\overline{M}_n(c)$. This proves the proposition. \square

Remark 2.3. For a real hypersurface M of $\overline{M}_n(c)$, the following two conditions are equivalent (see Proposition 5 in [7]):

- (i) The holomorphic distribution T_0 is integrable.
- (ii) $g((\phi A + A\phi)X, Y) = 0$ for any $X, Y \in T_0$.

Remark 2.4. Under the condition of Proposition 2.2, the shape operator A of M is η -parallel (see [7] Proposition 4).

For ruled real hypersurfaces in a complex space form, M. Kimura and S. Maeda obtained the following characterization theorem:

Theorem 2.5 (M. Kimura and S. Maeda [7]) Let M be a real hypersurface of $\mathbb{C}P_n(c)$. Then the shape operator A of M is η -parallel and the holomorphic distribution T_0 is integrable if and only if M is locally congruent to a ruled hypersurface of $\mathbb{C}P_n(c)$.

For a ruled hypersurface of $\overline{M}_n(c)$, S-S. Ahn, S-B. Lee, and Y-J. Suh obtained the following:

Theorem 2.6 (S-S. Ahn, S-B. Lee, and Y-J. Suh [1]) Let M be a connected real hypersurface of $\overline{M}_n(c)$, $c \neq 0$ and $n \geq 3$. If the shape operator A of M satisfies

$$g((\nabla_X A)Y, Z) = 0$$

and

$$g((A\phi - \phi A)X, Y) = 0$$

for any vector fields X, Y , and Z in T_0 , and the structure vector field ξ is not principal, then M is locally congruent to a ruled hypersurface.

3. Lemmas

In this section, we present some lemmas that we will use to prove our main theorem.

For the shape operators of real hypersurfaces in a non-flat complex space form $\overline{M}_n(c)$ ($c \neq 0$), we know the following:

Lemma 3.1 ([11], [13]) *Let M be a homogeneous real hypersurface of type (A) in a non-flat complex space form $\overline{M}_n(c)$ ($c \neq 0$). Then the shape operator A of M satisfies the following equations:*

$$\phi A - A\phi = 0, \quad (3.1)$$

$$A^2 - \alpha A - \frac{c}{4}I = -\frac{c}{4}\eta \otimes \xi, \quad (3.2)$$

$$(\nabla_X A)Y = -\frac{c}{4}\{\eta(Y)\phi X + g(\phi X, Y)\xi\}, \quad (3.3)$$

where α and I denote the principal curvature in the direction of the structure vector ξ and the identity mapping of TM , respectively.

Lemma 3.2 ([3]) *Let M be a homogeneous real hypersurface of type (A_0) or (B) in a non-flat complex space form $\overline{M}_n(c)$ ($c \neq 0$). Then the shape operator A of M satisfies the following equations:*

$$\phi A + A\phi + \frac{c}{\alpha}\phi = 0, \quad (3.4)$$

$$A^2 + \frac{c}{\alpha}A - \frac{c}{4}I = (\alpha^2 + \frac{3}{4}c)\eta \otimes \xi, \quad (3.5)$$

$$\begin{aligned} (\nabla_X A)Y = & -\frac{\alpha}{4}\{2\eta(X)(A\phi - \phi A)Y \\ & + \eta(Y)(A\phi - 3\phi A)X + g((A\phi - 3\phi A)X, Y)\xi\}. \end{aligned} \quad (3.6)$$

From Lemma 3.1, Lemma 3.2, Table 1 and Table 2, we have

Lemma 3.3. *Let M be a homogeneous real hypersurface of type (A_0) , (A_1) , or (B) in $\overline{M}_n(c)$ ($c \neq 0$). Then, the shape operator A of M satisfies the following equations for some nonzero constant a :*

$$\phi A + A\phi + a\phi = 0, \quad (3.7)$$

$$\begin{aligned} (\nabla_X A)Y = & \frac{c}{4a}\{2\eta(X)(2\phi A + a\phi)Y + \eta(Y)(4\phi A + a\phi)X \\ & + g((4\phi A + a\phi)X, Y)\xi\}. \end{aligned} \quad (3.8)$$

So, taking the covariant derivative of (3.8), we have the following:

Lemma 3.4. *Let M be a homogeneous real hypersurface of type (A_0) , (A_1) , or (B) in $\overline{M}_n(c)$ ($c \neq 0$). Then, the shape operator A of M satisfies the following equation for some nonzero constant a :*

$$\begin{aligned}
 g((\nabla_{X,Y}^2 A)Z, W) &= \frac{c}{4a} \{2g(\phi AX, Y)g((2\phi A + a\phi)Z, W) \\
 &\quad + g(\phi AX, Z)g((4\phi A + a\phi)Y, W) \\
 &\quad + g(\phi AX, W)g((4\phi A + a\phi)Y, Z)\}, \quad X, Y, Z, W \in T_0.
 \end{aligned}
 \tag{3.9}$$

For a ruled hypersurface in $\overline{M}_n(c)$ ($c \neq 0$), we have

Lemma 3.5. *Let M be a ruled hypersurface in $\overline{M}_n(c)$ ($c \neq 0$). Then, both-sides of (3.9) vanish.*

Proof For a ruled hypersurface M , the leaves of the distribution T_0 are totally geodesic both in M and $\overline{M}_n(c)$. Furthermore, the shape operator A of M is η -parallel (see [6]). From this it follows that

$$\begin{aligned}
 &g((\nabla_{X,Y}^2 A)Z, W) \\
 &= g(\nabla_X((\nabla_Y A)Z) - (\nabla_Y A)(\nabla_X Z), W) - g((\nabla_{\nabla_X Y} A)Z, W) \\
 &= 0, \quad X, Y, Z, W \in T_0.
 \end{aligned}$$

This means that the left side of (3.9) vanishes.

According to (2.10) and Remark 2.3, the right side of (3.9) also vanishes. This proves the lemma. \square

The following is known about the principal curvatures of a Hopf hypersurface:

Lemma 3.6 ([8], [13]) *Let M be a Hopf hypersurface of $\overline{M}_n(c)$ ($n \geq 2$, $c \neq 0$). Then the principal curvature α corresponding to the structure vector ξ is locally constant, and for any principal curvature vector $X \in T_0$ with $AX = \lambda X$, we have*

$$(2\lambda - \alpha)A\phi X = (\alpha\lambda + \frac{c}{2})\phi X.$$

4. Proof of Theorem

In this section we shall prove our main theorem.

Theorem 4.1. *Let M be a connected real hypersurface in a complex space form $\overline{M}_n(c)$ ($n \geq 3$, $c \neq 0$). Then the shape operator A satisfies the following equation for some nonzero constant a :*

$$\begin{aligned} g((\nabla_{X,Y}^2 A)Z, W) = & \frac{c}{4a} \{2g(\phi AX, Y)g((2\phi A + a\phi)Z, W) \\ & + g(\phi AX, Z)g((4\phi A + a\phi)Y, W) \\ & + g(\phi AX, W)g((4\phi A + a\phi)Y, Z)\}, \end{aligned} \quad (4.1)$$

$$X, Y, Z, W \in T_0,$$

if and only if M is locally congruent to one of the following:

- (A₀) a horosphere in $\mathbb{C}H_n(c)$;
- (A₁) a geodesic hypersphere in $\overline{M}_n(c)$ or a tube over a complex hyperbolic hyperplane $\mathbb{C}H_{n-1}(c)$ in $\mathbb{C}H_n(c)$;
- (B) a tube over a totally geodesic and totally real space form of real dimension n in $\overline{M}_n(c)$;
- (R) a ruled hypersurface in $\overline{M}_n(c)$.

By making use of the Codazzi equation (2.8), we find the following general formula:

$$\begin{aligned} & g((\nabla_{X,Y}^2 A)Z - (\nabla_{X,Z}^2 A)Y, W) \\ = & \frac{c}{4} \{g(\phi AX, Y)g(\phi Z, W) - g(\phi AX, Z)g(\phi Y, W) \\ & - 2g(\phi AX, W)g(\phi Y, Z)\}, \end{aligned} \quad (4.2)$$

on arbitrary tangent vectors $X, Y, Z, W \in T_0$. Therefore the condition (4.1) and (4.2) implies that

$$g(\phi AX, W)g((\phi A + A\phi + a\phi)Y, Z) = 0. \quad (4.3)$$

We assume here that $a \neq 0$.

In what follows e_1, \dots, e_{2n-2} denotes an orthonormal basis of T_0 at a point in M , and the index j runs from 1 to $2n - 2$. Letting $X = e_j$ and $W = \phi e_j$ in (4.3), and taking the summation on j , we have

$$(h - \alpha)g((\phi A + A\phi + a\phi)Y, Z) = 0, \quad (4.4)$$

where h and α denote the mean curvature of M and the function defined by $\alpha = g(A\xi, \xi)$, respectively. Furthermore, letting $Y = e_j$ and $Z = \phi e_j$ in (4.4) and taking the summation on j , we obtain

$$(h - \alpha)\{(h - \alpha) + (n - 1)a\} = 0. \quad (4.5)$$

From (4.5) either $h - \alpha = 0$ or $(h - \alpha) + (n - 1)a = 0$ holds on M , since M is connected and $a \neq 0$. We therefore divide the discussion into the following two cases:

Case 1. The equation $h - \alpha = 0$ holds on M .

Case 2. The equation $(h - \alpha) + (n - 1)a = 0$ holds on M .

We first consider Case 1, in which we have $(h - \alpha) + (n - 1)a = (n - 1)a \neq 0$. So, from (4.3), the following holds on M :

$$g(\phi AX, Y) = 0, \quad X, Y \in T_0. \quad (4.6)$$

This leads to

$$\begin{aligned} A\xi &= \alpha\xi + U, \\ AU &= g(U, U)\xi, \\ AX &= 0, \quad X \perp \xi, U, \end{aligned}$$

where the vector field U is defined by $U = A\xi - \alpha\xi$. This means that M is locally congruent to a ruled hypersurface of $\overline{M}_n(c)$ by Proposition 2.2 (see also [7]).

On the other hand, let M be a ruled hypersurface of $\overline{M}_n(c)$. Then, (4.1) holds by Lemma 3.5.

We next consider Case 2. In this case we have $h - \alpha \neq 0$. So, from (4.4),

$$(\phi A + A\phi + a\phi)X = -g(\phi U, X)\xi, \quad X \in T_0. \quad (4.7)$$

On the other hand, using (4.1), (2.7), and (2.9), we have

$$\begin{aligned}
& \frac{c}{4} \{g((\phi A + A\phi)Y, Z)g(\phi X, W) - g((\phi A + A\phi)X, Z)g(\phi Y, W) \\
& + g((\phi A + A\phi)Y, W)g(\phi X, Z) - g((\phi A + A\phi)X, W)g(\phi Y, Z)\} \\
& - \frac{c}{2} \{g((\phi A - A\phi)Z, W)g(\phi X, Y) + g((\phi A + A\phi)X, Y)g(\phi Z, W)\} \\
& - \frac{c}{a} g((\phi A + A\phi)X, Y)g(\phi AZ, W) + g(AY, Z)g(\frac{c}{4}X - A^2X, W) \\
& - g(AX, Z)g(\frac{c}{4}Y - A^2Y, W) - g(AX, W)g(\frac{c}{4}Y - A^2Y, Z) \\
& + g(AY, W)g(\frac{c}{4}X - A^2X, Z) = 0, \quad X, Y, Z, W \in T_0
\end{aligned} \tag{4.8}$$

(for details, see [12]).

Combining (4.7) with (4.8), we are led to

$$\begin{aligned}
& g(AY, Z)g(\frac{c}{4}X - A^2X, W) - g(AX, Z)g(\frac{c}{4}Y - A^2Y, W) \\
& - g(AX, W)g(\frac{c}{4}Y - A^2Y, Z) + g(AY, W)g(\frac{c}{4}X - A^2X, Z) = 0.
\end{aligned} \tag{4.9}$$

We assert that ξ is principal. We shall prove our assertion by *reductio ad absurdum*.

Let Ω be the open subset of M defined by $\Omega = \{p \in M \mid U(p) \neq 0\}$. In the following we assume that the set Ω is not empty and all discussion concerns the set Ω unless otherwise stated.

We restate the orthonormal frame field $e_1, e_2, \dots, e_{2n-1}$ in such a way that $e_1 = \xi$, $e_2 = U/\|U\|$, $e_3 = \phi e_2$, $e_{2i+1} = \phi e_{2i}$ ($i \geq 2$).

We now define the local differentiable functions $\alpha, \beta, \gamma, \delta$, and h_{ij} as follows:

$$\begin{aligned}
\alpha &= g(A\xi, \xi), \quad \beta = g(A\xi, e_2), \quad \gamma = g(Ae_2, e_2), \quad \delta = g(Ae_2, e_3), \\
h_{ij} &= g(Ae_i, e_j), \quad i, j = 1, 2, \dots, 2n-1.
\end{aligned}$$

Hereafter the index p runs $2, 4, \dots, 2(n-1)$ and p^* means $p^* = p+1$. We further assume that e_i ($i \geq 4$) are chosen in such a manner that

$$h_{ij} = \lambda_i \delta_{ij}. \quad (i, j \geq 4).$$

This is in fact possible by (4.7). Furthermore, the following are satisfied by (4.7):

$$g(Ae_3, e_3) = -(\gamma + a), \quad \lambda_{p^*} = -(\lambda_p + a), \quad p = 4, 6, \dots, 2(n-1).$$

Let us first demonstrate the following lemma:

Lemma 4.2. $h_{2p} = h_{2p^*} = 0$ ($p = 4, 6, \dots, 2(n-1)$).

Proof Letting $X = e_2$, $Y = \phi e_2$, $Z = e_p$, $W = e_2$ in (4.9), we have

$$\begin{aligned} & -\delta(\lambda_p + a)h_{2p} \\ & + \left\{ \gamma(\lambda_p - a) - \beta^2 - 2\gamma^2 - 2\delta^2 - \sum_p h_{2p}^2 - \sum_p h_{2p^*}^2 + \frac{c}{4} \right\} h_{2p^*} \quad (4.10) \\ & = 0. \end{aligned}$$

Letting $X = e_2$, $Y = \phi e_2$, $Z = e_{p^*}$, $W = \phi e_2$ in (4.9), we have

$$\begin{aligned} & \delta\lambda_p h_{2p} \\ & + \left\{ 2\delta^2 + 2(\gamma + a)^2 + \sum_p h_{2p}^2 + \sum_p h_{2p^*}^2 - \frac{c}{4} - (\gamma + a)(\lambda_p + 2a) \right\} h_{2p^*} \\ & = 0. \end{aligned} \quad (4.11)$$

Letting $X = e_2$, $Y = \phi e_2$, $Z = e_{p^*}$, $W = e_2$ in (4.9), we have

$$\begin{aligned} & \left\{ \gamma(\lambda_p + 2a) + \beta^2 + 2\gamma^2 + 2\delta^2 + \sum_p h_{2p}^2 + \sum_p h_{2p^*}^2 - \frac{c}{4} \right\} h_{2p} \\ & + \delta\lambda_p h_{2p^*}^2 = 0. \end{aligned} \quad (4.12)$$

Letting $X = e_2$, $Y = \phi e_2$, $Z = e_p$, $W = \phi e_2$ in (4.9), we have

$$\begin{aligned} & \left\{ (\gamma + a)(\lambda_p - a) + 2\delta^2 + 2(\gamma + a)^2 + \sum_p h_{2p}^2 + \sum_p h_{2p^*}^2 - \frac{c}{4} \right\} h_{2p} \\ & + \delta(\lambda_p + a)h_{2p^*} = 0. \end{aligned} \quad (4.13)$$

From (4.10) and (4.11), we have

$$a\delta h_{2p} + \{a(\lambda_p - \gamma) + \beta^2\} h_{2p^*} = 0. \quad (4.14)$$

From (4.12) and (4.13), we have

$$\{a(\lambda_p + \gamma + a) - \beta^2\} h_{2p} + a\delta h_{2p^*} = 0. \quad (4.15)$$

Letting $X = e_2$, $Y = e_p$, $Z = e_{p^*}$, $W = \phi e_2$ in (4.9), we have

$$\{\delta h_{2p} + (\lambda_p - \gamma)h_{2p^*}\} h_{2p^*} = 0. \quad (4.16)$$

Letting $X = \phi e_2$, $Y = e_p$, $Z = e_{p^*}$, $W = e_2$ in (4.9), we have

$$\{(\lambda_p + \gamma + a)h_{2p} + \delta h_{2p^*}\} h_{2p} = 0. \quad (4.17)$$

From (4.15) and (4.17),

$$\beta^2 h_{2p} = 0,$$

and from (4.14) and (4.16),

$$\beta^2 h_{2p^*} = 0.$$

Since $\beta \neq 0$, the lemma holds. \square

Secondly, we prove the following lemma:

Lemma 4.3. $\delta = 0$.

Proof We shall prove the lemma by reductio ad absurdum. We assume that $\delta \neq 0$ is satisfied. Then, letting $X = e_2$, $Y = e_p$, $Z = e_p$, $W = \phi e_2$ in (4.9) and using Lemma 4.2, we are led to

$$\lambda_p^2 + a\lambda_p - \frac{c}{4} = 0. \quad (4.18)$$

This leads to $\lambda_p \neq 0$ since $c \neq 0$. Letting $X = e_2$, $Y = e_p$, $Z = e_p$, $W = e_2$ in (4.9), we have

$$\gamma(\lambda_p^2 - \frac{c}{4}) - (\beta^2 + \gamma^2 + \delta^2)\lambda_p = 0. \quad (4.19)$$

Combining (4.18) with (4.19), we have

$$a\gamma + \beta^2 + \gamma^2 + \delta^2 = 0. \quad (4.20)$$

Letting $X = \phi e_2$, $Y = e_p$, $Z = e_p$, $W = \phi e_2$ in (4.9), we have

$$(\gamma + a)(\lambda_p^2 - \frac{c}{4}) + \lambda_p \left\{ \delta^2 + (\gamma + a)^2 - \frac{c}{4} \right\} = 0. \quad (4.21)$$

Combining (4.18) with (4.21), we have

$$\delta^2 + (\gamma^2 + a\gamma - \frac{c}{4}) = 0. \quad (4.22)$$

Letting $X = e_2$, $Y = e_{p^*}$, $Z = e_{p^*}$, $W = \phi e_2$ in (4.9), we have

$$(\gamma + a) \left\{ (\lambda_p + a)^2 - \frac{c}{4} \right\} - (\lambda_p + a) \left\{ \delta^2 + (\gamma + a)^2 - \frac{c}{4} \right\} = 0. \quad (4.23)$$

Combining (4.18) with (4.23), we have

$$\{\gamma(\gamma + a) + \delta^2\} \lambda_p + a(\delta^2 + \gamma^2 + a\gamma - \frac{c}{4}) = 0. \quad (4.24)$$

From (4.22), (4.24), and $\lambda_p \neq 0$, we are led to

$$c = 0,$$

which is a contradiction, so $\delta = 0$ must be satisfied. \square

Thirdly, we establish the following lemma:

Lemma 4.4.

$$\lambda_p = \lambda_{p^*} = -\frac{a}{2}, \quad \gamma = -\left(\frac{c}{2a} + a\right).$$

Proof Letting $X = e_2$, $Y = \phi e_2$, $Z = \phi e_2$, $W = e_2$ in (4.9) and using Lemma 4.2 and Lemma 4.3, we have

$$(\gamma + a)\beta^2 + (2\gamma + a)(\gamma^2 + a\gamma - \frac{c}{4}) = 0. \quad (4.25)$$

Equation (4.21) is reduced to

$$(\lambda_p + \gamma + a) \left\{ \lambda_p(\gamma + a) - \frac{c}{4} \right\} = 0. \quad (4.26)$$

Also, (4.23) is reduced to

$$(\lambda_p - \gamma) \left\{ (\lambda_p + a)(\gamma + a) + \frac{c}{4} \right\} = 0. \quad (4.27)$$

Letting $X = e_p$, $Y = e_{p^*}$, $Z = e_{p^*}$, $W = e_p$ in (4.9), we have

$$(2\lambda_p + a)(\lambda_p^2 + a\lambda_p - \frac{c}{4}) = 0. \quad (4.28)$$

We assert that $\lambda_p \neq \gamma$. If $\lambda_p = \gamma$ were satisfied, we would have $(\gamma + a)\beta^2 = 0$ from (4.25) and (4.28). Since $\beta \neq 0$, we further would have $\gamma = -a$. Then, from (4.26) and (4.28) we would be led to $c = 0$ which is a contradiction, so $\lambda_p \neq \gamma$ must be satisfied.

We assert that $\lambda_p \neq -(\gamma + a)$. If this were not so, we would have $(\gamma + a)\beta^2 = 0$ from (4.25) and (4.27). Since $\beta \neq 0$, we further would have

$\gamma = -a$. Then, from (4.26) and (4.28) we would be led to $c = 0$ which is a contradiction, so $\lambda_p \neq -(\gamma + a)$ must be satisfied.

Therefore from (4.26) and (4.27) we get $\lambda_p = -\frac{a}{2}$, $\gamma = -(\frac{c}{2a} + a)$. This completes the proof. \square

We end this section with a proof of our main theorem. From Lemma 4.4, (4.25) is reduced to

$$2a^2\beta^2 + (a^2 + c)^2 = 0$$

which is a contradiction, so the structure vector ξ must be principal. This leads to our main theorem as follows. Since ξ is principal, (4.7) is reduced to

$$\phi A + A\phi + a\phi = 0. \quad (4.29)$$

Then, from Lemma 3.6, M has at most three distinct constant principal curvatures. So, owing to Theorem K and Theorem B, M is locally congruent to a homogeneous real hypersurface of type (A) or (B) in $\overline{M}_n(c)$ ($c \neq 0$). Among these homogeneous real hypersurfaces, (4.29) is satisfied by type (A₀), (A₁), or (B). This concludes the proof of the theorem by the arguments above.

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